

## Two Examples for critical Template Problems (from Tokyo)

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Here are my examples from Tokyo regarding the indirect instantiation. The first is unique for separate translation units. The second was formulated using different translation units, which I reformulated for namespace usage.

```
// *****

// unit 1                                // unit 2

class D;                                  class D { int dd; };
class A { D* aa; };                       class A;
                                           class B {}

                                           A* f(B);

template <class T>                         template <class T>
void foo (T t)                             void foo (T t);
{
    f(t)->aa->dd++;
}

                                           void bar ()
                                           {
                                           foo( B() );
                                           }

// *****

// unit 1                                // unit 2                                // unit 3

template <class T>                         template <class T>
void f(T*);                                void g(T*);
template <class T>                         template <class T>
void g(T*);                                void g(T* t)
                                           {
                                           h(t);
                                           }

class A1{};                                class B1{};
class A2{};                                class B2{};

void h(A1*);                                void h(B1*);
void h(A2*);                                void h(B2*);

A1 *a1;                                    B1 *b1;
A2 *a2;                                    B2 *b2;

                                           template <class T>
void f(T* t)                                void g(T* t)
                                           {
                                           g(t);
                                           g(b1);
                                           }

                                           // template <>
void bar()                                // void f<B2>(B2* t)
{                                           void foo (B2* t)
{                                           {
    f(a1);                                g(t);
    g(a2);                                g(b1);
}                                           }
}

// ***** and here the version using namespaces (assume the three
```

```

// columns are a single translation unit )

// *****

namespace N2 {
template <class T>
void f(T*);
} // N2
namespace N3 {
template <class T>
void g(T*);
} // N3

namespace N1 {
class A1{};
class A2{};

void h(A1*);
void h(A2*);

A1 *a1;
A2 *a2;

void bar()
{
    N2::f(a1);
    N3::g(a2);
}

} // N1

namespace N2 {
class B1{};
class B2{};

void h(B1*);
void h(B2*);

B1 *b1;
B2 *b2;

template <class T>
void f(T* t)
{
    N3::g(t);
    N3::g(b1);
}

// template <>
// void f<B2>(B2* t)
void foo (B2* t)
{
    N3::g(t);
    N3::g(b1);
}

} // N2

namespace N3 {
template <class T>
void g(T* t)
{
    h(t);
}

} // N3

```